

Characteristic Formulae for Liveness Properties of Non-terminating CakeML Programs

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ITP, Portland OR, September 12th 2019


```
while(true) do {  
    print("y\n");  
}
```

```
while(true) do {  
    print("y\n");  
}
```

Safety: yes never prints anything but y\n

Liveness: yes always eventually prints another y\n

Smashed together:

yes diverges, printing exactly an infinite stream of y\n

```
{true}
```

```
while(true) do {  
    print("y\n");  
}
```

```
{false}
```

Hoare Logic
~~Characteristic Formulae~~ for Liveness
Properties of Non-terminating ~~CakeML~~

WHILE Programs

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Hoare Logic
~~Characteristic Formulae~~ for Liveness
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WHILE Programs



Oversimplifies the paper!

Two kinds of post-conditions

$\{P\} e \{Trm Q\}$

$\{P\} e \{Div S\}$

Two kinds of post-conditions

$\{P\} e \{Trm\ Q\}$

Bog-standard total correctness
Hoare triple!

“If P holds initially, then e
terminates in a state
satisfying Q”

$\{P\} e \{Div\ S\}$

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“If P holds initially, then e
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$\{P\} e \{Div\ S\}$

“If P holds initially, then e runs forever,
producing a trace satisfying S”

Two kinds of post-conditions

$\{P\} e \{Trm\ Q\}$

Bog-standard total correctness
Hoare triple!

“If P holds initially, then e
terminates in a state
satisfying Q”

State predicates

$\{P\} e \{Div\ S\}$

“If P holds initially, then e runs forever,
producing a trace satisfying S”

Trace predicate

Two kinds of post-conditions

$\{P\} e \{Trm\ Q\}$

Bog-standard total correctness
Hoare triple!

“If P holds initially, then e
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satisfying Q”

state => bool

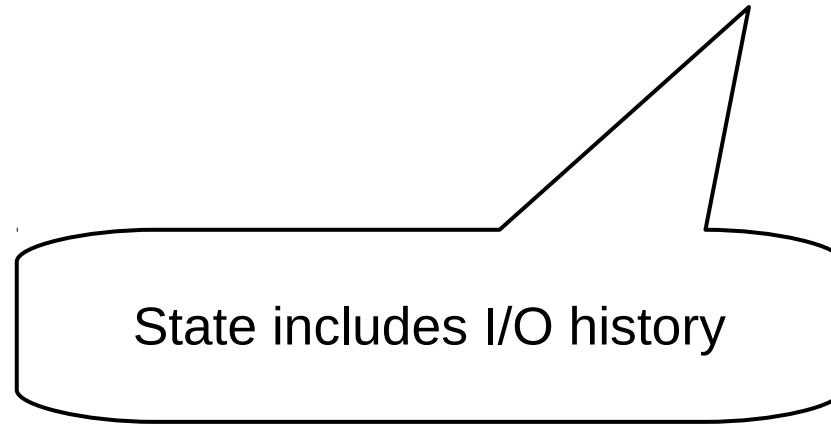
$\{P\} e \{Div\ S\}$

“If P holds initially, then e runs forever,
producing a trace satisfying Q”

io_event llist => bool

States

```
type state = heap x io_event list
```



```
{h=[]}
```

```
print(s)
```

```
{Trm(h=[print s])}
```

States

```
type state = heap x io_event list
```



Abbreviates $\lambda(s,h). h=[]$

```
{h=[]}
```

```
print(s)
```

```
{Trm(h=[print s])}
```

The WHILE rule

$$P \Rightarrow I_0 \wedge h=h_0$$

$$\forall i. \{I_i \wedge h=[]\} e \{\text{Trm}(I_{i+1} \wedge h=h_{i+1})\}$$

$$S(h_0 \cdot h_1 \cdot h_2 \cdot \dots)$$

$$\{P\} \text{ while}(\text{true}) \text{ do } e \{\text{Div } S\}$$

The WHILE rule

Witnesses:

h_n I/O trace from the n:th loop iteration

l_n (internal) state after the n:th loop iteration

$$P \Rightarrow l_0 \wedge h = h_0$$

$$\forall i. \{l_i \wedge h = []\} e \{ \text{Trm}(l_{i+1} \wedge h = h_{i+1}) \}$$

$$S(h_0 \cdot h_1 \cdot h_2 \cdot \dots)$$

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The WHILE rule

$$P \Rightarrow I_0 \wedge h=h_0$$

$$\forall i. \{I_i \wedge h=[]\} \in \{\text{Trm}(I_{i+1} \wedge h=h_{i+1})\}$$

$$S(h_0 \cdot h_1 \cdot h_2 \cdot \dots)$$

$$\{P\} \text{ while } (\text{true}) \text{ do } \{ \text{Div } S \}$$

Actually more like

$$S(\text{flatten}(\text{lgenerate } (\lambda n. h_n)))$$

yes again

```
{h = []}
  while(true) do {
    print("y\n");
  }
{Div( $\lambda t. t = [\text{print}("y\n")]^\omega$ )}
```

yes again

```
{h = []}
  while(true) do {
    print("y\n");
  }
{Div( $\lambda t. t = [\text{print}(\text{"y\n"})]^\omega$ )}
```

Proof: apply the WHILE rule with

$$I_n = \lambda x. \text{true}$$
$$h_0 = []$$
$$h_n = [\text{print}(\text{"y\n"})] \text{ otherwise}$$

In summary

- 😊 Conservative extension
- 😊 Existing proofs can be replayed verbatim
- 😊 Supports silent divergence
- 😊 No clocks, program counters or special silent actions
- 😬 Divergence and termination not treated uniformly
- 😬 No good story for internal non-determinism
- 😬 Incomplete (without extra structural rules)

c.f. [Nakata and Uustalu 2010]

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Yes, but...

```
\begin{itemize}
```

```
\item We don't actually use Hoare Logic...
```

```
\item ...but characteristic formulae (CF), and
```

```
\item CakeML doesn't even have while!
```

```
\end{itemize}
```


The WHILE rule reloaded

$$P \Rightarrow I_0 \wedge h=h_0$$

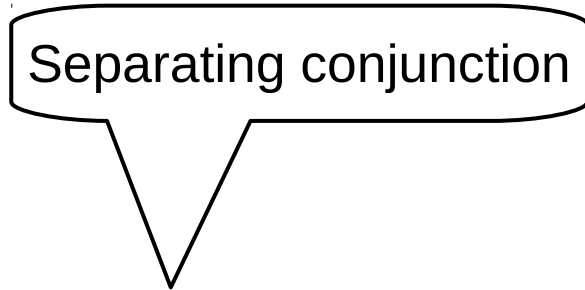
$$\forall i. \{I_i \wedge h=[]\} \text{ e } \{\text{Trm}(I_{i+1} \wedge h=h_{i+1})\}$$

$$S(h_0 \cdot h_1 \cdot h_2 \cdot \dots)$$

$$\{P\} \text{ while}(\text{true}) \text{ do } \text{e } \{\text{Div } S\}$$

The WHILE rule reloaded

Separating conjunction


$$P \Rightarrow I_0 * h = h_0$$
$$\forall i. \{I_i * h = []\} \text{ e } \{\text{Trm}(I_{i+1} * h = h_{i+1})\}$$
$$S(h_0 \cdot h_1 \cdot h_2 \cdot \dots)$$

$$\{P\} \text{ while}(\text{true}) \text{ do } e \{\text{Div } S\}$$

The WHILE rule reloaded

Expressions have return values

$$P \Rightarrow I_0 * h = h_0$$
$$\forall i. \{I_i * h = []\} f(x_i) \{Trm(x_{i+1})(I_{i+1} * h = h_{i+1})\}$$
$$S(h_0 \cdot h_1 \cdot h_2 \cdot \dots)$$

$$\{P\} \text{ repeat } f \ x_0 \ \{\text{Div } S\}$$

fun repeat f x = repeat f (f x)

The WHILE rule reloaded

$$P \Rightarrow I_0 * h = h_0$$

$$\forall i. \{I_i * h = []\} f(x_i) \{ \text{Trm}(x_{i+1})(I_{i+1} * h = h_{i+1}) \}$$

$$S(h_0 \cdot h_1 \cdot h_2 \cdot \dots)$$

$$\{P\} \text{ repeat } f \ x_0 \{ \text{Div } S \}$$

This is a theorem about Hoare triples, not a postulate.

Hoare triples are shallowly embedded,
defined in terms of CakeML's operational semantics

CF (Characteristic formulae)

Verification condition generator for impure functional programs
[Charguéraud 2010]

Adapted to CakeML in previous work [Guéneau et al. 2016]

Workhorse function:

$$\text{cf} : \text{exp} \Rightarrow (\text{state} \Rightarrow \text{bool}) \Rightarrow$$
$$(\text{result} \Rightarrow \text{state} \Rightarrow \text{bool}) \Rightarrow \text{bool}$$

CF (Characteristic formulae)

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Workhorse function:

$$\text{cf} : \text{exp} \Rightarrow (\text{state} \Rightarrow \text{bool}) \Rightarrow \\ (\text{result} \Rightarrow \text{state} \Rightarrow \text{bool}) \Rightarrow \text{bool}$$

Intuition: to prove a Hoare triple

$$\{P\} e \{Q\}$$

it suffices to show

$$\text{cf } e \ P \ Q$$

CF (before)

```
Datatype result =  
  Val v  
| Exn v
```

CF (after)

```
Datatype result =  
  Val v  
| Exn v  
| Div (io_event llist)
```

CF (before)

$$\begin{aligned} \text{cf } (e1; e2) P Q = & \\ \text{local}(\exists R. \text{cf } e1 P R \wedge & \\ \quad \forall \text{res. is_value}(\text{res}) \Rightarrow \text{cf } e2 (R \text{ res}) Q \wedge & \\ \quad \neg \text{is_value}(\text{res}) \Rightarrow R(\text{res}) \Rightarrow Q(\text{res}) & \\) & \end{aligned}$$

CF (after)

$$\begin{aligned} \text{cf } (e1; e2) P Q = & \\ \text{local}(\exists R. \text{cf } e1 P R \wedge & \\ \quad \forall \text{res. is_value}(\text{res}) \Rightarrow \text{cf } e2 (R \text{ res}) Q \wedge & \\ \quad \neg \text{is_value}(\text{res}) \Rightarrow R(\text{res}) \Rightarrow Q(\text{res}) & \\) & \end{aligned}$$

CF (before)

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No difference whatsoever!*

CF (after)

$$\begin{aligned} \text{cf } (e1; e2) P Q = & \\ \text{local}(\exists R. \text{cf } e1 P R \wedge & \\ \quad \forall \text{res. is_value}(\text{res}) \Rightarrow \text{cf } e2 (R \text{ res}) Q \wedge & \\ \quad \neg \text{is_value}(\text{res}) \Rightarrow R(\text{res}) \Rightarrow Q(\text{res}) & \\) & \end{aligned}$$

CF

Theorem (soundness)


If

$cf \in P \ Q$

then

$\{P\} \in \{Q\}$

Reconciling repeat

 `fun yes() =
 repeat (fn _ => print("y\n")) ()`

Reconciling repeat



```
fun yes() =  
  repeat (fn _ => print("y\n")) ()
```



```
fun yes() =  
  (print("y\n"); yes())
```

Reconciling repeat

Theorem (folk)

For every tail-recursive function f
there exists a non-recursive function g ,
such that whenever $f(x)$ diverges,

repeat $g\ x$

diverges in an observationally equivalent way.

Reconciling repeat

Theorem (folk?)

For every tail-recursive function f
there exists a non-recursive function g ,
such that whenever $f(x)$ diverges,

repeat $g\ x$

diverges in an observationally equivalent way.

A verified program transformation automatically produces such a g
before the WHILE rule is applied

Limitations of repeat transformation

🤖 Only supports tail recursion

Not a problem in practice:

```
fun f(x) = f(x) + 1
```

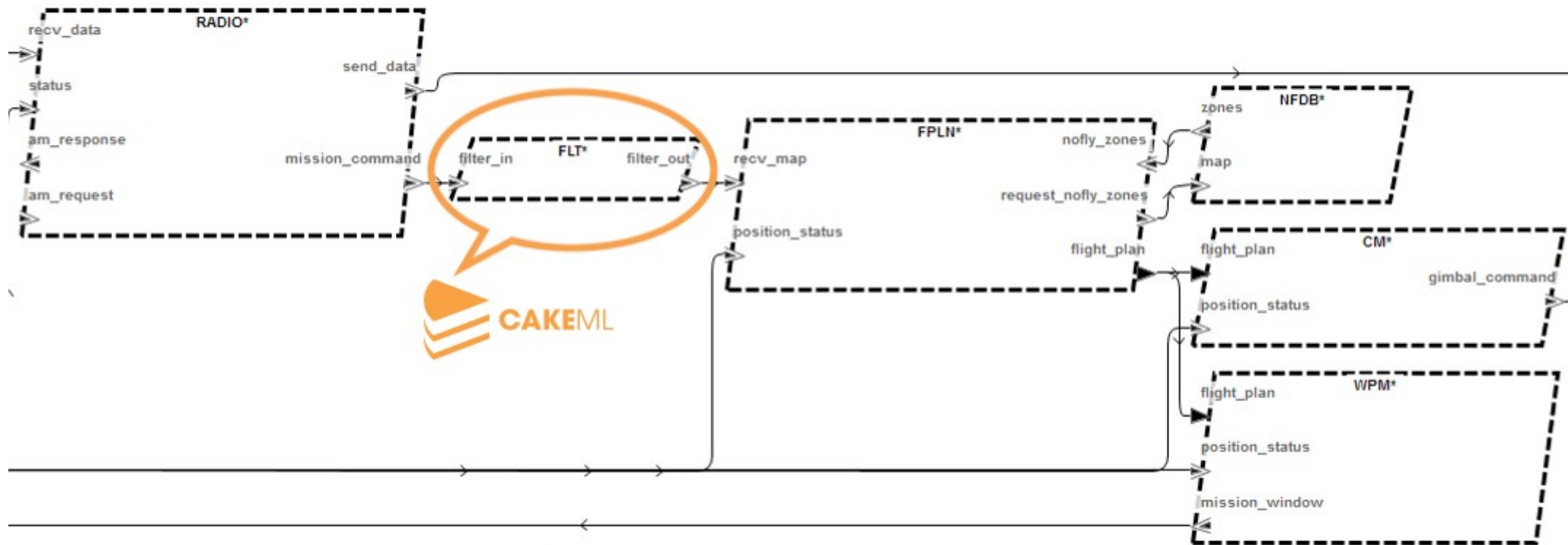
diverges in theory, but overflows the stack in practice.

🤖 No support for mutual recursion (yet)

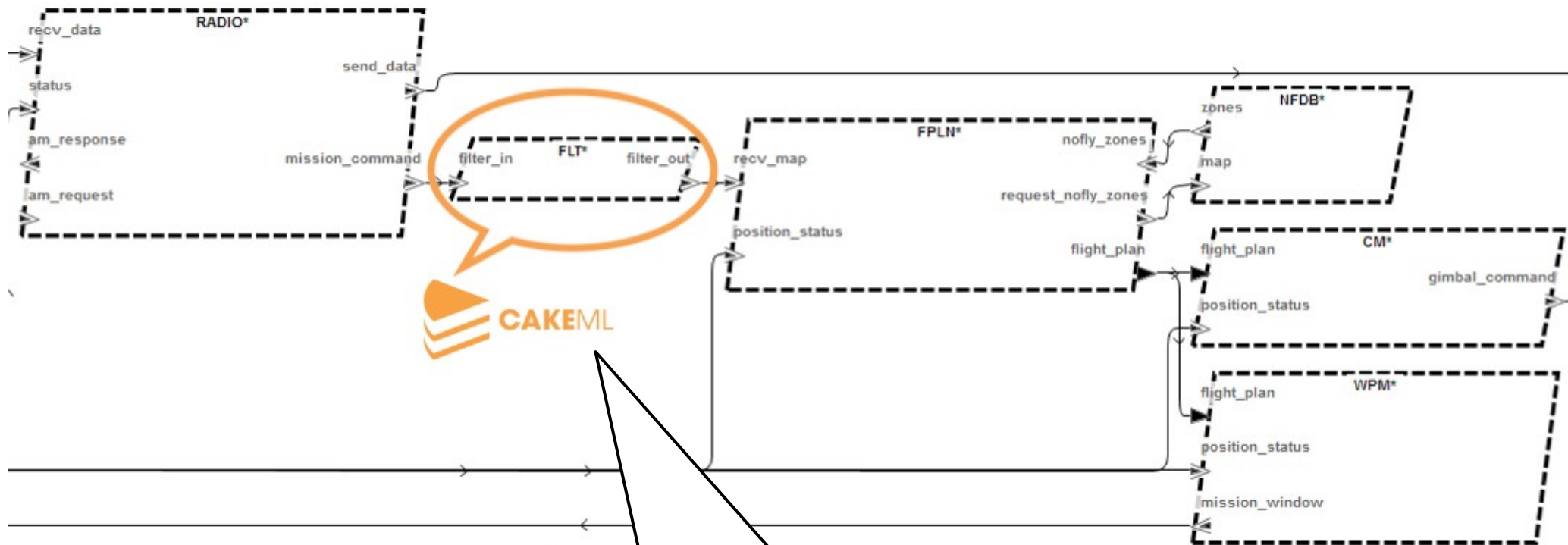
🤖 No support for weird recursion through the store

```
val f = ref (fn () => ());  
val g = (fn () => !f ());  
val _ = (f := g; g());
```

Case study: verified filters



Case study: verified filters



The filter *cannot* terminate
(If it does, the UAV can't be contacted)

Conclusion

😊 Conservative extension of CF to support liveness proofs for non-terminating programs.

😊 Formalised in HOL4, integrated into CakeML ecosystem

<https://code.cakeml.org>

😊 Thanks for listening!